



Bell & Gossett
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SPECIFICATIONS

TFSPECEMTX R2

TECHNOFORCE e-MTX

PART 1 **GENERAL**

1.1 SECTION INCLUDES

- A. Variable Speed Pumping Package
- B. Pump Control Panel
- C. Variable Frequency Drive
- D. Sensor Transmitters
- E. Sequence of Operation

1.2 REFERENCES

- A. AWWA - American Water Works Association
- B. ANSI - American National Standards Institute
- C. ASTM - American Standards for Testing Materials
- D. HI - Hydraulic Institute
- E. ASME - American Society of Mechanical Engineers
- F. UL - Underwriters Laboratories
- G. ISO - International Standards Organization
- H. NEMA - National Electrical Manufacturers Association
- I. ETL - Electrical Testing Laboratories
- J. CSA - Canadian Standards Association
- K. NEC - National Electrical Code
- L. IEC - International Electrotechnical Commission
- M. NSF - NSF International

1.3 SUBMITTALS

A. SUBMITTALS SHALL INCLUDE THE FOLLOWING:

- 1. System summary sheet
- 2. Sequence of operation
- 3. Shop drawing indicating dimensions, required clearances and location and size of each field connection
- 4. Power and control wiring diagrams
- 5. System profile analysis including variable speed pump curves and system curve. The analysis shall also include pump, motor, pump efficiencies, horsepower and kilowatt/hour consumption.
- 6. Pump data sheets

B. Submittals must be specific to this project. Generic submittals will not be accepted.

1.4 QUALITY ASSURANCE

- A. The pumping package shall be assembled by the pump manufacturer. An assembler of pumping systems not actively engaged in the design and construction of centrifugal pumps shall not be considered a pump manufacturer. The manufacturer shall assume "Unit Responsibility" for the complete pumping package. Unit responsibility shall be defined as responsibility for interface and successful operation of all system components supplied by the pumping system manufacturer.
- B. The manufacturer shall have a minimum of 30 years experience in the design and construction of packaged pumping systems, and over 50 years in active design/production of centrifugal pumps.
- C. The pumping system shall be factory tested to the job specific condition points prior to shipment.
- D. Bidders shall comply with all sections of this specification relating to packaged pumping systems. Any deviations from this specification shall be bid as a voluntary alternate clearly defined in writing. If no exceptions are noted, the supplier or contractor shall be bound by these specifications.
- E. A copy of manufacturer's certificate of insurance shall be made available upon request showing as a minimum, general liability coverage of \$1,000,000, and an excess liability coverage of \$10,000,000.
- F. The pumping package shall be certified by an approved independent testing and certification organization as being compliant with the requirements of NSF/ANSI 61 for potable drinking water and NSF-61 Annex G for low lead content.
- G. Manufacturer shall be listed by UL as a manufacturer of packaged pumping systems under UL/cUL category QCZJ.
- H. Manufacturer shall be listed by UL as a manufacturer of control panels under UL 508A.
- I. The manufacturer's production facility shall be certified by an approved independent testing and certification organization as being compliant with the requirements of NSF/ANSI 61 and NSF-61 Annex G. The manufacturing facility shall be subjected to periodic inspections and audits.

PART 2 PRODUCTS

2.1 ACCEPTABLE MANUFACTURERS

Subject to compliance with these specifications, the following manufacturers shall be acceptable:

- 1. Goulds Water Technology
- 2. Pre-approved equal

2.2 MANUFACTURED UNITS

- A. Furnish and install as shown on the plans a TechnoForce Variable Speed Booster System as manufactured by Goulds Water Technology or approved equal. Suction and discharge headers shall be constructed of 304 series stainless steel.
- B. Manufacturer shall be listed by Underwriters Laboratories as a manufacturer of packaged pumping systems.
- C. The entire pumping package shall be NSF/ANSI/NSF-61 certified for potable drinking water and NSF-61 Annex G for a wetted area, weighted average lead content = 0.25%.
- D. The control system shall include, as a minimum, the programmable logic station controller, variable frequency drives, a manifold mounted 4-20mA pressure transducer and any additional equipment as specified or as required to properly execute the sequence of operation.
- E. System shall require only suction, discharge and drain connections and single point power connections from a service entrance disconnect.
- F. All components shall be mounted and shipped as a single unit.
- G. Pumps shall be manufactured by Xylem.
- H. The discharge of each pump shall be fitted with a control valve appropriate for station operation. Each pump and discharge valve assembly shall also be equipped with isolation valves so that the pump can be serviced while system is still filled.

- I. Pressure gauges shall be installed on the suction and discharge headers.
- J. Piping shall be sized so that water velocity shall not exceed 10.0 ft/sec in either the branches or manifolds.
- K. Pumps shall be protected from thermal accumulation via individual thermal relief mechanisms.

2.3 COMPONENTS

A. TechnoForce Variable Speed Pump Logic Controller

1. The TechnoForce pump logic controller shall be listed by the Underwriter's Laboratory and bear the UL/cUL label, and shall be certified by BACnet Testing Laboratory and bear the BTL label. The controller shall be specifically designed for packaged pressure booster applications.
2. The variable speed pump control logic shall be capable of accelerating a pump to rated speed (Staging) and decelerating pump to a stop or a specific safe speed (De-Staging). It shall employ various methods to perform staging and de-staging including process variable (PV), end-of-curve EOC), power staging, force de-staging, flow de-staging, time de-staging, and alternation.
3. The programmable logic controller (PLC) and operator interface shall be one integrated unit capable of controlling from 1 to 8 pumps, and supporting English, Spanish and French languages. The controller interface shall have an environmental operating range of 0 to 50°C (<2000 m or 6666 ft), and a 90% RH rating at 40°C.
- 4 The standard 10" color touchscreen interface shall have a landscape format, VGA (1280 x 720) resolution, and a LED backlight. Analog input resolution shall be 12-bit minimum. The interface shall have multi-level password protection capability to configure and modify pump and motor parameters. A Quick Start-up Menu screen shall facilitate easy start-up.
5. Interfacing through the color touchscreen display shall be supported with (2) RS485 connections, Ethernet interface, X2X Link interface, Powerlink interface, and a USB 2.0 port.
6. The pressure booster application software shall be held non-volatile 2 GB flash memory with the capability of preventing accidental loss of data and values due to voltage surges and spikes. In the event of a complete power outage, all factory preset, or last saved data values, shall remain stored and available for recall by the operator.
7. The variable speed pump logic program shall provide safeguards against damaging hydraulic conditions including:
 - a. Under-voltage (auto reset configuration option permits 3X fault resets)
 - b. Over-voltage (auto reset configuration option permits 3X fault resets)
 - c. Over-current (auto reset configuration option permits 3X fault resets)
 - d. End-of-curve protection (requires option Flow Meter)
 - e. Low or high system failure
 - f. Low or high suction pressure
8. The variable speed pump logic software program ability to detect fault conditions includes:
 - a. Pump failure
 - b. VFD run failure
 - c. VFD communication failure
 - d. Low and high system pressure
 - e. Low and high suction pressure
 - f. Loss of prime (requires optional loss-of-prime sensor/switch)
 - g. Low suction prime (requires low suction prime line)
 - h. Low and high water (tank) level (requires optional level switches)
 - i. Low inlet pressure (requires optional low inlet pressure switch)

9. As a minimum, the controller shall have the Inputs and Outputs:
 - a. Digital (8) programmable digit inputs (DI). One DI is dedicated to Local/Remote switch, and rest shall be configurable
 - b. Three (3) 4-20mA programmable analog inputs (AI) for suction and system pressure transducers and optional flow meter.
 - c. One (1) analog output, 4-20mA signal.
 - d. Two (2) solid state digital outputs
 - e. Two (2) programmable relay outputs, 230 VAC/5A rating
10. The pump controller shall be capable of communicating with the Building Management System (BMS) by either (1) hard-wire or (2) a communications protocol.
 - a. Hard wire: The following communication features shall be provided to the BAS via 4-20mA analog output signals and digital input/outputs:
 - i. Remote system Start/Stop (dry contact supplied by BAS)
 - ii. General Alarm digital (1 ea - relay output from pump controller)
 - iii. Process variable (PV) or VFD speed (1 ea - 4-20mA analog output supplied by pump controller)
 - iv. System On/Off status (1 ea - relay output supplied by pump controller)
 - b. Communications Protocol: The followings BMS communication protocols are supported:
 - i. Modbus RTU
 - ii. Modbus TCP
 - iii. BACnet MSTP
 - iv. BACnet IP
 - v. Johnson N2
 - c. The following communication is supported over BACnet using a RS485 port:
 - i. System start/stop; input and output (Start/Stop)
 - ii. System operation mode (Auto/Manual)
 - iii. System sequence alternation (Yes/No)
 - iv. System pressure (0-span)
 - v. Suction Pressure (0-span)
 - vi. System power (0-span)
 - vii. Analog input #1-thru-#4 (0-span)
 - viii. System flow; GPM; Requires optional flow meter (0-span)
 - ix. Individual Set point #1-thru-#4 (0-span)
 - x. Individual Drive current (0-span)
 - xi. Individual drive power; KW (0-span)
 - xii. Individual pump off (Alarm/OK)
 - xiii. Individual pump enabled (Enabled/disabled)
 - xiv. Speed (%)
 - xv. General alarm

- xvi. Individual VFD failure (Failure/OK)
 - xvii. Individual pump failure (Failure/OK)
 - xviii. Analog Input #1-thru-#4 failure (Failure/OK)
 - xix. Individual sensor failure
 - xx. System reset request (Yes/No)
 - xxi. Lead pump number (1 to 8)
 - xxii. Active zone number (1-4)
- d. The PLC shall support baud rates (kbits/sec) of 9600, 19200, 38400, and 115,200.
11. Sensors, Transducers
- a. Discharge pressure transducer (Standard default)
 - b. Suction pressure transducer shall be connected pump logic and shut down booster if minimum pressure falls below set point (Standard default).
 - c. A backup redundant discharge pressure transducer shall provide continued operation if the primary transducer fails (Optional). A warning light signal shall be given.
 - d. Low suction pressure Switch (Optional)
 - e. Flow meter (Optional)
 - f. Loss of prime assembly (Optional)
 - g. Ship loose transducers; up to 4 zone permissible (Optional)
12. No Flow Shutdown (NFSD)
- a. The pump logic control shall be capable of shutting down the system without the need for a flow meter/switch, once no flow is detected. This system will restart once the system pressure equals a 'restart PSI' set point pressure.
13. Pipe Fill Mode:
- a. On initial start-up, the booster will slowly fill the system with water. Once the controller detects that the system has been filled, the system pressure is built up over a pre-determined ramp-up time.
14. Condensate Return-to-Cooling Tower Control Package (Option)
- a. The pump control logic shall be capable of pumping feed water to a site cooling tower while utilizing condensate water captured in a holding tank provided by others. The controller shall monitor the water level in the tank utilizing 'ship-loose' high and low water level switches mounted to the tank. Back-up level switches will be provided as for safety.
 - b. If not enough water is detected in the tank a relay shall be provided in the control panel capable of opening/closing a main water solenoid valve fill pipe connected to the tank. The controller shall monitor the condensate water
15. Jockey
- a. The programmable logic controller (PLC) and operator interface shall be one integrated unit capable of controlling from 1 to 8 pumps, up to 2 of which can be configured as jockey pumps, and supporting English, Spanish, and French languages. The controller interface shall have an environment operating range of 0 to 50°C (<2000 m or 6666 ft), and a 90% RH rating at 40°C.

- 16. Screen
 - a. The standard 10" color touchscreen interface shall have a landscape format, VGA (1280 x 720) resolution, and a LED backlight. Analog input resolution shall be 12-bit minimum. The interface shall have multi-level password protection capability to configure and modify pump and motor parameters. A Quick Start-up Menu screen shall facilitate easy start-up.
- 17. Generator Mode
 - a. The system shall have the ability to run at a reduced power consumption allowing for the use of a generator in the event power is lost to the site. The generator must be sized appropriately.
- 18. Dynamic Flow Loss Compensation – ASHRAE 90.1-210 Compliant
 - a. If a pressure sensor is not located remotely as the point of the critical fixture, the pump logic controller shall be capable of using algorithms to simulate a sensor located at the critical fixture, such that the fiction loss associated with varying flow through the system is compensated for by corresponding set point adjustments. A flow meter shall not be required. The controller will log the last 40 real time set point changes.
- 19. Data Logging
 - a. The controller shall log last 100 instances covering

Alarm Log	All alarms
Event Log	All events
Pump Log	Every time a pump is toggled ON/OFF logs time and date. Also includes total runtime of each pump.
Data Log	Logs current, lowest and highest values with date and time for all sensors. It includes total power consumption (kWh) and total flow of the system.
Operation Log	Logs every time the mode is changed (automatic/manual), VFD failures, power cuts and resumes to the system.
Exercise Log	Log time and date every time a pump is exercised
Set point Log	Every time the pressure set point is changed, log old and new set points along with time and date
Alternation Log	Every time system alternates, log the new sequence with date & time.
System reset Log	Every time system resets, log the resetting method with date & time
Service Log	Log calculated de-stage speed and total operation time of the system
Error Log	Display B&R system log

- 20. Other Control Features and Functionality is provided:
 - a. Time and Date set-up
 - b. Optional Flow Meter
 - c. Alarm horn (Optional)
 - d. Alarm Status

B. TECHNOLOGIC VARIABLE FREQUENCY DRIVE

1. Description

- a. This specification covers complete variable frequency drives (VFDs) designated on the drawing schedules to be variable speed. All standard and optional features shall be included within the VFD panel. The Bell & Gossett Technologic drive hardware shall be manufactured by Danfoss.
- b. The VFD shall be rated NEMA 1 or NEMA 12 as required on the schedule. The VFD shall have been evaluated by UL and found acceptable for mounting in a plenum or other air handling compartment. Manufacturer shall supply a copy of the UL plenum evaluation upon request.
- c. The VFD shall be tested to UL 508C. The appropriate UL label shall be applied. When the VFDs are to be located in Canada, C-UL certifications shall apply. VFD shall be manufactured in ISO 9001, 2000 certified facilities.
- d. The VFD shall be CE marked and conform to the European Union ElectroMagnetic Compatibility directive.
- e. The VFD shall be UL listed for a short circuit current rating of 100 kA and labeled with this rating.
- f. The VFD manufacturer shall supply the VFD and all necessary controls as herein specified.

2. Components

- a. The VFD shall convert incoming fixed frequency three-phase AC power into an adjustable frequency and voltage for controlling the speed of three-phase AC motors. The motor current shall closely approximate a sine wave. Motor voltage shall be varied with frequency to maintain desired motor magnetization current suitable for the driven load and to eliminate the need for motor de-rating.
- b. When properly sized, the VFD shall allow the motor to produce full rated power at rated motor voltage, current, and speed without using the motor's service factor. VFDs utilizing sine weighted/ coded modulation (with or without 3rd harmonic injection) must provide data verifying that the motors will not draw more than full load current during full load and full speed operation.
- c. The VFD shall include an input full-wave bridge rectifier and maintain a fundamental (displacement) power factor near unity regardless of speed or load.
- d. The VFD shall have a dual 5% impedance DC link reactor on the positive and negative rails of the DC bus to minimize power line harmonics and protect the VFD from power line transients. The chokes shall be nonsaturating. Swinging chokes that do not provide full harmonic filtering throughout the entire load range are not acceptable. VFDs with saturating (non-linear) DC link reactors shall require an additional 3% AC line reactor to provide acceptable harmonic performance at full load, where harmonic performance is most critical.
- e. The VFD's full load output current rating shall meet or exceed NEC Table 430-150. The VFD shall be able to provide full rated output current continuously, 110% of rated current for 60 seconds and 120% of rated torque for up to 0.5 second while starting.
- f. A programmable automatic energy optimization selection feature shall be provided standard in the VFD. This feature shall automatically and continuously monitor the motor's speed and load to adjust the applied voltage to maximize energy savings.
- g. Output power circuit switching shall be able to be accomplished without interlocks or damage to the VFD.
- h. An automatic motor adaptation algorithm shall measure motor stator resistance and reactance to optimize performance and efficiency. It shall not be necessary to run the motor or de-couple the motor from the load to perform the test.
- i. Galvanic isolation shall be provided between the VFD's power circuitry and control circuitry to ensure operator safety and to protect connected electronic control equipment from damage caused by voltage spikes, current surges, and ground loop currents. VFDs not including either

galvanic or optical isolation on both analog I/O and discrete digital I/O shall include additional isolation modules.

- j. VFD shall minimize the audible motor noise through the use of an adjustable carrier frequency. The carrier frequency shall be automatically adjusted to optimize motor and VFD operation while reducing motor noise. VFDs with fixed carrier frequency are not acceptable.

3. Protective features

- a. A minimum of Class 20 I2t electronic motor overload protection for single motor applications shall be provided. Overload protection shall automatically compensate for changes in motor speed.
- b. Protection against input transients, loss of AC line phase, output short circuit, output ground fault, over voltage, under voltage, VFD over temperature and motor over temperature. The VFD shall display all faults in plain language. Codes are not acceptable.
- c. Protect VFD from input phase loss. The VFD should be able to protect itself from damage and indicate the phase loss condition. During an input phase loss condition, the VFD shall be able to be programmed to either trip off while displaying an alarm, issue a warning while running at reduced output capacity, or issue a warning while running at full commanded speed. This function is independent of which input power phase is lost.
- d. Protect from under voltage. The VFD shall provide full rated output with an input voltage as low as 90% of the nominal. The VFD will continue to operate with reduced output, without faulting, with an input voltage as low as 70% of the nominal voltage.
- e. Protect from over voltage. The VFD shall continue to operate without faulting with a momentary input voltage as high as 130% of the nominal voltage.
- f. The VFD shall incorporate a programmable motor preheat feature to keep the motor warm and prevent condensation build up in the motor when it is stopped in a damp environment by providing the motor stator with a controlled level of current.
- g. VFD shall include a "signal loss detection" algorithm with adjustable time delay to sense the loss of an analog input signal. It shall also include a programmable time delay to eliminate nuisance signal loss indications. The functions after detection shall be programmable.
- h. VFD shall function normally when the keypad is removed while the VFD is running. No warnings or alarms shall be issued as a result of removing the keypad.
- i. VFD shall catch a rotating motor operating forward or reverse up to full speed without VFD fault or component damage.
- j. Selectable over-voltage control shall be provided to protect the drive from power regenerated by the motor while maintaining control of the driven load.
- k. VFD shall include current sensors on all three output phases to accurately measure motor current, protect the VFD from output short circuits, output ground faults, and act as a motor overload. If an output phase loss is detected, the VFD will trip off and identify which of the output phases is low or lost.
- l. If the temperature of the VFD's heat sink rises to 80°C, the VFD shall automatically reduce its carrier frequency to reduce the heat sink temperature. It shall also be possible to program the VFD so that it reduces its output current limit value if the VFD's temperature becomes too high.
- m. In order to ensure operation during periods of overload, it must be possible to program the VFD to automatically reduce its output current to a programmed value during periods of excessive load. This allows the VFD to continue to run the load without tripping.
- n. The VFD shall have temperature controlled cooling fan(s) for quiet operation, minimized losses, and increased fan life. At low loads or low ambient temperatures, the fan(s) may be off even when the VFD is running.
- o. The VFD shall store in memory the last 10 alarms. A description of the alarm, and the date and time of the alarm shall be recorded.

- p. When used with a pumping system, the VFD shall be able to detect no-flow situations, dry pump conditions, and operation off the end of the pump curve. It shall be programmable to take appropriate protective action when one of the above situations is detected.

4. Interior Features

- a. Hand, Off and Auto keys shall be provided to start and stop the VFD and determine the source of the speed reference. It shall be possible to either disable these keys or password protect them from undesired operation.
- b. There shall be an "Info" key on the keypad. The Info key shall include "on-line" context sensitive assistance for programming and troubleshooting.
- c. The VFD shall be programmable to provide a digital output signal to indicate whether the VFD is in Hand or Auto mode. This is to alert the Building Automation System whether the VFD is being controlled locally or by the Building Automation System.
- d. Password protected keypad with alphanumeric, graphical, backlit display can be remotely mounted. Two levels of password protection shall be provided to guard against unauthorized parameter changes.
- e. All VFDs shall have the same customer interface. The keypad and display shall be identical and interchangeable for all sizes of VFDs.
- f. To set up multiple VFDs, it shall be possible to upload all setup parameters to the VFD's keypad, place that keypad on all other VFDs in turn and download the setup parameters to each VFD. To facilitate setting up VFDs of various sizes, it shall be possible to download from the keypad only size independent parameters. Keypad shall provide visual indication of copy status.
- g. Display shall be programmable to communicate in multiple languages including English, Spanish and French.
- h. A red FAULT light, a yellow WARNING light and a green POWER-ON light shall be provided. These indications shall be visible both on the keypad and on the VFD when the keypad is removed.
- i. A quick setup menu with factory preset typical HVAC parameters shall be provided on the VFD. The VFD shall also have individual Fan, Pump, and Compressor menus specifically designed to facilitate start-up of these applications.
- j. The VFD's PID controller shall be able to actively adjust its setpoint based on flow. This allows the VFD to compensate for a pressure feedback sensor which is located near the output of the pump rather than out in the controlled system.
- k. Floating point control interface shall be provided to increase/decrease speed in response to contact closures.
- l. Five simultaneous meter displays shall be available. They shall include at a minimum, frequency, motor current, motor voltage, VFD output power, VFD output energy, VFD temperature in degrees, actual process variable and set point among others.
- m. Programmable Sleep Mode shall be able to stop the VFD. When its output frequency drops below set "sleep" level for a specified time, when an external contact commands that the VFD go into Sleep Mode, or when the VFD detects a no-flow situation, the VFD may be programmed to stop. When the VFD's speed is being controlled by its PID controller, it shall be possible to program a "wake-up" feedback value that will cause the VFD to start. To avoid excessive starting and stopping of the driven equipment, it shall be possible to program a minimum run time before sleep mode can be initiated and a minimum sleep time for the VFD.
- n. A run permissive circuit shall be provided to accept a "system ready" signal to ensure that the VFD does not start until dampers or other auxiliary equipment are in the proper state for VFD operation. The run permissive circuit shall also be capable of initiating an output "run request" signal to indicate to the external equipment that the VFD has received a request to run.

- o. VFD shall be programmable to display feedback signals in appropriate units, such as inches of water column (in-wg), pressure per square inch (psi) or temperature (°F).
- p. VFD shall be programmable to sense the loss of load. The VFD shall be programmable to signal this condition via a keypad warning, relay output and/or over the serial communications bus. To ensure against nuisance indications, this feature must be based on motor torque, not current, and must include a proof timer to keep brief periods of no load from falsely triggering this indication.

5. Standard Inputs and Outputs

- a. Four dedicated, programmable digital inputs shall be provided for interfacing with the systems control and safety interlock circuitry.
- b. Two terminals shall be programmable to act either as digital outputs or additional digital inputs.
- c. Two programmable relay outputs, Form C 240 V AC, 2 A, shall be provided for remote indication of VFD status.
 - (i) Each relay shall have an adjustable on delay / off delay time.
- d. Two programmable analog inputs shall be provided that can be either direct-or-reverse acting.
 - (i) Each shall be independently selectable to be used with either an analog voltage or current signal.
 - (ii) The maximum and minimum range of each shall be able to be independently scalable from 0 to 10 V dc and 0 to 20 mA.
 - (iii) A programmable low-pass filter for either or both of the analog inputs must be included to compensate for noise.
 - (iv) The VFD shall provide front panel meter displays programmable to show the value of each analog input signal for system set-up and troubleshooting,
- e. One programmable analog current output (0/4 to 20 mA) shall be provided for indication of VFD status. This output shall be programmable to show the reference or feedback signal supplied to the VFD and for VFD output frequency, current and power. It shall be possible to scale the minimum and maximum values of this output.
- f. It shall be possible through serial bus communications to read the status of all analog and digital inputs of the VFD.
- g. It shall be possible to command all digital and analog output through the serial communication bus.
- h. Optional Control and Monitoring Inputs and Outputs
 - (i) It shall be possible to add optional modules to the VFD in the field to expand its analog and digital inputs and outputs.
 - (ii) These modules shall use rigid connectors to plug into the VFD's control card.
 - (iii) The VFD shall automatically recognize the option module after it is powered up. There shall be no need to manually configure the module.
 - (iv) Modules may include such items as:
 - (v) Additional digital outputs, including relay outputs
 - (vi) Additional digital inputs
 - (vii) Additional analog outputs
 - (viii) Additional analog inputs, including Ni or Pt temperature sensor inputs
- i. It shall be possible through serial bus communications to control the status of all optional analog and digital outputs of the VFD.
- j. A real-time clock shall be an integral part of the VFD.
- k. It shall be possible to use this to display the current date and time on the VFD's display.
- l. Ten programmable time periods, with individually selectable ON and OFF functions shall be available. The clock shall also be programmable to control start/stop functions, constant speeds, PID parameter setpoints and output relays. It shall be possible to program unique events that occur only during

normal work days, others that occur only on non-work days, and others that occur on specific days or dates. The manufacturer shall provide free PC-based software to set up the calendar for this schedule.

- m. All VFD faults shall be time stamped to aid troubleshooting.
- n. It shall be possible to program maintenance reminders based on date and time, VFD running hours, or VFD operating hours.
- o. The real-time clock shall be able to time and date stamp all faults recorded in the VFD fault log.
- p. The VFD shall be able to store load profile data to assist in analyzing the system demand and energy consumption over time.
- q. The VFD shall include a sequential logic controller to provide advanced control interface capabilities. This shall include:
 - (i) Comparators for comparing VFD analog values to programmed trigger values
 - (ii) Logic operators to combine up to three logic expressions using Boolean algebra
 - (iii) Delay timers
 - (iv) A 20-step programmable structure
- r. The VFD shall include a Cascade Controller which allows the VFD to operate in closed loop set point (PID) control mode one motor at a controlled speed and control the operation of 3 additional constant speed motor starters.

6. Serial Communications

- a. The VFD shall include a standard EIA-485 communications port and capabilities to be connected to the following serial communication protocols at no additional cost and without a need to install any additional hardware or software in the VFD:
 - (i) Johnson Controls Metasys N2
 - (ii) Modbus RTU
 - (iii) BACnet MS/TP
- b. The VFD shall have provisions for an optional 24 V DC back-up power interface to power the VFD's control card. This is to allow the VFD to continue to communicate to the building automation system even if power to the VFD is lost.

7. Adjustments

- a. The VFD shall have a manually adjustable carrier frequency that can be adjusted in 0.5 kHz increments to allow the user to select the desired operating characteristics. The VFD shall also be programmable to automatically reduce its carrier frequency to avoid tripping due to thermal loading.
- b. Four independent setups shall be provided.
- c. Four preset speeds per setup shall be provided for a total of 16.
- d. Each setup shall have two programmable ramp up and ramp down times. Acceleration and deceleration ramp times shall be adjustable over the range from 1 to 3,600 seconds.
- e. Each setup shall be programmable for a unique current limit value. If the output current from the VFD reaches this value, any further attempt to increase the current produced by the VFD will cause the VFD to reduce its output frequency to reduce the load on the VFD. If desired, it shall be possible to program a timer which will cause the VFD to trip off after a programmed time period.
- f. If the VFD trips on one of the following conditions, the VFD shall be programmable for automatic or manual reset: external interlock, under-voltage, over-voltage, current limit, over temperature, and VFD overload.
- g. The number of restart attempts shall be selectable from 0 through 20 or infinitely and the time between attempts shall be adjustable from 0 through 600 seconds.
- h. An automatic "start delay" may be selected from 0 to 120 seconds. During this delay time, the VFD shall be programmable to either apply no voltage to the motor or apply a DC braking current if desired.

- i. Four programmable critical frequency lockout ranges to prevent the VFD from operating the load at a speed that causes vibration in the driven equipment shall be provided. Semi-automatic setting of lockout ranges shall simplify the set-up.
8. Service Conditions
 - a. Ambient temperature, continuous, full speed, full load operation:
 - (i) -10 to 45°C (14 to 113°F) through 125 HP @ 460 and 600 volt, through 60 HP @ 208 volt
 - (ii) -10 to 40°C (14 to 104°F) 150 HP and larger
 - b. 0 to 95% relative humidity, non-condensing.
 - c. Elevation to 3,300 feet without derating.
 - d. AC line voltage variation, -10 to +10% of nominal with full output.
 - e. No side clearance shall be required for cooling.
 - f. All power and control wiring shall be done from the bottom.
 - g. All VFDs shall be plenum rated.
 9. Quality Assurance
 - a. To ensure quality, the complete VFD shall be tested by the manufacturer. The VFD shall drive a motor connected to a dynamometer at full load and speed and shall be cycled during the automated test procedure.
 10. VFD shall utilize a full wave rectifier to convert three phase AC to a fixed DC voltage. Power factor shall remain above 0.98 regardless of speed or load. VFD's employing power factor correction capacitors shall not be acceptable.
 11. An internal line reactor (5% impedance) shall be provided to lower harmonic distortion of the power line and to increase the fundamental power factor.
 12. The VFD shall be suitable for elevations to 3300 feet above sea level without derating. Maximum operating ambient temperature rating shall not be greater than 104°F. VFD shall be suitable for operation in environments up to 95% non-condensing humidity.
 13. The VFD shall be capable of displaying the following information in plain English via an alphanumeric display:
 - a. Output Frequency
 - b. Output Voltage
 - c. Motor Current
 - d. Kilowatts per hour
 - e. Fault identification with text
 - f. Percent torque
 - g. Percent power
 - h. RPM
 14. The VFD shall have the ability to automatically restart after an over-current, overvoltage, under-voltage, or loss of input signal protective trip. The number of restart attempts, trial time, and time between reset attempts shall be programmable.
 15. Three (3) programmable critical frequency lockout ranges to prevent the VFD from operating the load continuously at an unstable speed.
 16. Operator Control Panel (Keypad)
 - a. Each VFD shall be equipped with a front mounted operator control panel (keypad) consisting of a backlit, alphanumeric, graphic display and a keypad with keys for Start/Stop, Local/Remote, Up/Down and Help. Two (2) Softkeys will be provided which change functionality depending upon the position within the parameter hierarchy or state of panel.

- b. All parameter names, fault messages, warnings and other information shall be displayed in complete English words or Standard English abbreviations to allow the user to understand what is being displayed without the use of a manual or cross-reference table.
- c. The Display shall have contrast adjustment provisions to optimize viewing at any angle.
- d. The control panel shall provide a real time clock for time stamping events and fault conditions.
- e. The control panel shall include a feature for uploading parameter settings to control panel memory and downloading from the control panel to the same Drive or to another Drive.
- f. All Drives throughout the entire power range shall have the same customer interface, including digital display, and keypad, regardless of horsepower rating.
- g. The keypad shall be able to be installed or removed from the drive while it is powered, capable of remote mounting, and shall have its own non-volatile memory.

17. Protective Functions

- a. For each programmed warning and fault protection function, the Drive shall display a message in complete English words or Standard English abbreviations. The three (3) most recent fault messages along with time, current, speed, voltage, frequency and DI Status shall be stored in the Drive's fault history. The last ten (10) fault names shall be stored in Drive memory.
- b. The Drive shall include internal MOV's for phase to phase and phase to ground line voltage transient protection.
- c. Output short circuit withstand rating and ground fault protection rated for 100,000 AIC shall be provided per UL508C without relying on line fuses. Motor phase loss protection shall be provided.
- d. The Drive shall provide electronic motor overload protection qualified per UL508C.
- e. Protection shall be provided for AC line or DC bus overvoltage at 130% of maximum rated or under voltage at 65% of min. rated and input phase loss.
- f. A power loss ride through feature will allow the Drive to remain fully operational after losing power as long as kinetic energy can be recovered from the rotating mass of the motor and load.

18. Integrated Drive Disconnects

- a. 3-Phase: Individual integrated drive fused disconnects shall have exterior operators.
- b. Single-Phase: Individual integrated drive disconnects shall have exterior operators and external fusing.

19. Variable Speed System Sequence of Operation

- a. The system shall consist of a pump logic controller with multi-pump parallel operation control, duty-standby pump selection, automatic alternation and automatic transfer to the standby pump upon pump/VFD failure.
- b. The pumping system shall start upon the closure of customer's contact when the pump logic controller Mode of Operation is in REMOTE.
- c. When the pump logic controller mode in LOCAL, the pumping system shall operate automatically. d. Each sensor/transmitter shall send a 4-20mA signal to the pump logic controller, indicative of process variable condition.
- e. When the set point is satisfied by the process variable, the pump speed shall remain constant at the optimum energy consumption level.
- f. When the process variable exceeds the allowable drift from the set point for a set time the pump controller shall automatically start the next lag pump and continue in this fashion as necessary to satisfy system demand. To maintain system set point the controller will operate the pumps synchronously or sequentially to ensure maximum energy conservation.
- g. As demand is satisfied, the controller shall automatically stop lag pumps as necessary to conserve energy.

- h. In the event of a pump failure or a VFD fault, the pump logic controller automatically initiates a timed sequence of operation to start the redundant pump/VFD set in the variable speed mode.
- i. In the event of the failure of a zone sensor/transmitter, its process variable signal shall be removed from the scan/compare program. The redundant zone sensor/transmitters, if available, shall remain in the scan/compare program for control.
- j. PUMP or VFD hard fault shall be flash continuously on the display on the operator interface of the pump logic controller until the fault has been corrected and the controller has been manually reset.
- k. When the system is satisfied, the pump controller shall shutdown the single running lead pump without the need of a flow sensor/switch or hydropneumatic tank and enter energy saving / no flow shutdown mode.

20. Electrical

- a. Pump Logic Controller Enclosure. Main station disconnect shall have a through door operator and shall be sized as shown in the technical data sheet. Individual integrated fusible drive disconnects shall have exterior operators, and shall be sized as shown in the technical data sheet. Station disconnect panel shall be housed in a NEMA 1 enclosure as standard. The control enclosure shall be constructed of 14-gauge steel and the back plate assembly shall be constructed of 14-gauge steel.
- b. Controls and Enclosure. The control panel with controls shall be built in accordance with NEC, and shall comply with UL standards. Pump station manufacturer shall be authorized under UL508A to manufacture its own control panels. All equipment and wiring shall be mounted within the enclosure and each device shall be labeled with proper identification. All adjustments and maintenance shall be accessible from the front of the control enclosure. A complete wiring circuit diagram and legend with terminals, components, and wiring completely identified shall be provided. Main disconnect shall be interlocked with door.
- c. Station shall have a short circuit current rating (SCCR) OF 5000A

21. Sensor / Transmitters

- a. Pressure transducer shall be utilized for providing all pressure signals for the pump control logic. Pressure transducer shall be a solid-state bonded strain gage type with an accuracy of $< \pm 0.5\%$ BFSL and constructed of 316 stainless steel. Transducer shall be rated for a pressure of 300 psi and shall provide gauge pressure output, rather than an absolute. Pressure transducer constructed of plastic is not acceptable. Pressure transducer shall be 4-20mA analog type with 10-28 VDC supply range shall utilize a packard type connector to prevent moisture intrusion and include surge protection against voltage spikes.

22. Flowmeter, when specified and shown in the plans

- a. Provide a Goulds Water Technology ST-104 field mounted flow sensor transmitter as indicated on the plans. Unit shall transmit an isolated 4-20 mA dc signal indicative of process variable to the pump logic controller via standard two wire 24 VDC system. Unit shall consist of an insertion probe and separately mounted transmitter. The unit shall be accurate to within 1% of flow rate from 1.0 ft/sec to 30.0 ft/sec and shall withstand a static pressure of 200.0 psi g with negligible change in output.

23. Variable Speed System Sequence of Operation

- a. The system shall consist of a Technologic 1500 pump logic controller with multi-pump parallel operation control, duty-standby pump selection, automatic alternation and automatic transfer to the standby pump upon pump/VFD failure.
- b. The pumping system shall start upon the closure of customer's contact when the pump logic controller Mode of Operation is in REMOTE.
- c. When the pump logic controller mode in LOCAL, the pumping system shall operate automatically.
- d. Each sensor/transmitter shall send a 4-20mA signal to the Technologic 1500 pump logic controller, indicative of process variable condition.

- e. When the set point is satisfied by the process variable, the pump speed shall remain constant at the optimum energy consumption level.
- f. The pump controller shall automatically start the lag pumps as necessary to satisfy system demand.
- g. As demand is satisfied, the controller shall automatically stop lag pumps as necessary to conserve energy.
- h. In the event of a pump failure or a VFD fault, the pump logic controller automatically initiates a timed sequence of operation to start the redundant pump/VFD set in the variable speed mode.
- i. In the event of the failure of a zone sensor/transmitter, its process variable signal shall be removed from the scan/compare program. The redundant zone sensor/transmitters, if available, shall remain in the scan/compare program for control.
- j. PUMP or VFD fault shall be continuously scrolled through the display on the operator interface of the pump logic controller until the fault has been corrected and the controller has been manually reset.
- k. When the system is satisfied, the pump controller shall shut down the single running lead pump and enter energy saving / no flow shutdown mode.

C. MECHANICAL

1. Pump Station Frame and Piping

- a. Framing shall be designed and fabricated to provide structural support for all attached equipment, and provide anchor bolt support. The base shall supply sufficient rigidity to withstand the stresses of reasonable and competent transportation to site, off loading, installation, and operation.
- b. Piping shall be constructed from 304 stainless steel, schedule 10 or heavier pipe as required to maintain a 3 to 1 pressure safety factor (including 1/16" corrosion allowance).

2. Stainless Steel Vertical Multistage Pumps

- a. Goulds Water Technology's e-SV vertical multi-stage pump, compliant to ANSI/NSF-61 Annex G, premium efficient motor - standard NEMA design 56C, JM, or TC frame.
- b. AISI 304 wetted components
- c. Impeller: AISI 304
- d. Diffuser: AISI 304
- e. Shaft: AISI 316 (sizes 1 - 22SV) • Duplex ASTM-A182 (sizes 33-92SV)
- f. External sleeve: AISI 304
- g. Pump body: ASTM Class 35/40B Cast Iron, 304 SS or 316L SS
- h. Seal housing: AISI 304
- i. Mechanical seal: all material options NSF/ANSI-61 compliant

3. Centrifugal Pumps

- a. Goulds Water Technology NPE or e-SH end suction pump.
- b. 316L construction
- c. Premium efficient 3-PH motor, ODP or TEFC enclosure. NEMA design T-frame or JM.

4. Isolation Ball Valves

- a. Isolation ball valves shall be certified to NSF-61 for use with potable drinking water.
- b. Isolation ball valves shall be certified as low lead having wetted surface area with a weighted average lead content < 0.25%.
- c. Valves shall be rated for 600 psi WOG / 150 psi WSP for valves 1/4" to 2" and 400 psi WOG / 125 psi WSP for valves 2-1/2" to 4".

- d. Seats and stem packing shall be virgin PTFE. Stem shall be bottom loaded blowout proof design with fluorocarbon elastomer O-ring to prevent stem leaks.
 - e. Valves shall be 2-piece full port design.
5. Isolation Grooved Butterfly Valves
- a. Valves shall be certified to NSF-61 for use with potable drinking water.
 - b. Valve bodies shall be nylon coated ductile iron conforming to ASTM A536 with integral neck and ISO mounting top.
 - c. The disc shall be encapsulated with Gr. E EPDM for cold and hot water services.
 - d. Valves shall be rated for 300 psi CWP
6. Isolation Lug Style Butterfly Valve
- a. Valve shall be certified to NSF-61 for use with potable drinking water.
 - b. Valve body shall be made of ASTM 536 ductile iron and will be coated with an FDA approved epoxy. Valve face to face dimensions shall comply with API 609 and MSS-SP-67.
 - c. Disc shall be made of ASTM A-351 stainless steel. Shaft shall be made of 316SS.
 - d. Bushing shall be made of a Teflon®-Darcon inner liner bonded to fiberglass-epoxy resin outer shell.
 - e. Seat shall be EPDM.
 - f. Valve shall be rated to 200 psi WOG.
7. Threaded Check Valves
- a. All valve metallic components shall be 316SS.
 - b. Seat shall be Viton.
 - c. Valve shall be rated for 400 psi WOG.
8. Wafer Style Silent Check Valve
- a. The valve body shall be constructed of ASTM A126 Class B cast iron for Class 125/250 (lead free).
 - b. The seat and double guided disc shall be ASTM B584, C87600 silicon bronze.
 - c. The compression spring shall be ASTM A313 Type 316 Stainless Steel.
 - d. NSF/ANSI 61 & 372 certification
 - e. The valve design shall incorporate a center guided, spring loaded disc, guided at opposite ends and having a short linear stroke that generates a flow area equal to the nominal valve size.
 - f. The operation of the valve shall not be affected by the position of installation. The valve shall be capable of operating in the horizontal or vertical positions with the flow up or down.
 - g. All component parts shall be field replaceable without the need of special tools. A replaceable guide bushing shall be provided and held in position by the spring. The spring shall be designed to withstand 100,000 cycles without failure and provide a cracking pressure of 0.5 psi.
 - h. The valve disc shall be concave to the flow direction providing for disc stabilization, maximum strength, and a minimum flow velocity to open the valve.
 - i. The valve disc and seat shall have a seating surface finish of 16 micro-inch or better to ensure positive seating at all pressures. The leakage rate shall not exceed the allowable rate for metal seated valves allowed by AWWA Standard C508 or 1 oz (30 ml) per hour per inch (mm) of valve diameter.
 - j. The valve flow way shall be contoured and unrestricted to provide full flow areas at all locations within the valve. Cv flow coefficients shall be equal to or greater than specified below and verified by an independent testing laboratory.
 - k. The valves shall be hydrostatically tested at 1.5 times their rated cold working pressure and seat tested at the valve CWP.

9. Sensor / Transmitters

- a. Pressure transducer shall be utilized for providing all pressure signals for the pump control logic. Pressure transducer shall be a solid-state bonded strain gage type with an accuracy of $< \pm 0.5\%$ BFSL and constructed of 316 stainless steel. Transducer shall be rated for a pressure of 300 psi and shall provide gauge pressure output, rather than an absolute. Pressure transducer constructed of plastic is not acceptable. Pressure transducer shall be 4-20mA analog type with 10-28 VDC supply range, shall utilize a packard type connector to prevent moisture intrusion, and include surge protection to protect against voltage spikes.

Valve Size Inches (mm)	Wafer Style Cv
2 (50)	43
2.5 (65)	88
3 (80)	130
4 (100)	228
5 (125)	350
6 (150)	520

10. Flowmeter

- a. Provide a Goulds Water Technology ST-104 field mounted flow sensor transmitter as indicated on the plans. Unit shall transmit an isolated 4-20 mA dc signal indicative of process variable to the pump logic controller via standard two wire 24 VDC system. Unit shall consist of an insertion probe and separately mounted transmitter. The unit shall be accurate to within 1% of flow rate from 1 to 30 fps and shall withstand a static pressure of 200 PSI with negligible change in output.

11. Pressure Gauges

- a. Gauges shall be provided for the suction and discharge manifold.
- b. Accuracy shall be $\pm 1.5\%$
- c. Bourdon tube and connection shall be constructed of 316SS.
- d. Case, bezel and internals shall be constructed of 316SS.
- e. Gauge shall be filled with glycerin in order to dampen pulsation and vibration and to provide lubrication to the internal parts.
- f. Gauge range shall be selected to cover the largest operating range for the specific conditions and pump selected.

12. Flange Bolts

- a. Bolts shall be zinc plated and shall meet ASTM Grade A193 B7.

13. Paint

- a. Standard finish coat shall be acrylic enamel to a thickness of no less than 3 mils.

PART 3 EXECUTION**3.1 INSTALLATION**

- A. Install equipment in accordance with manufacturer's instructions. The contractor shall determine the appropriate method for mounting, securing and plumbing the package in accordance with applicable state, federal and local building and plumbing codes. Isolation valves are required by the manufacturer on suction and discharge lines, valves by others.
- B. The contractor shall align the pump and motor shafts to within the manufacturer's recommended tolerances prior to system start-up.
- C. Power supply wiring, as required, as well as installation methods, shall be the responsibility of the electrical contractor. All wiring shall be performed per applicable state, federal and local codes.
- D. Control wiring for remote mounted switches and sensor / transmitters shall be the responsibility of the controls contractor. All wiring shall be performed per manufacturer's instructions and applicable state, federal and local codes.

3.2 DEMONSTRATION/TRAINING

- A. Start-up and training of the packaged pumping system shall be the responsibility of the distributor.

3.3 WARRANTY

- A. The manufacturer shall warrant the water pumping system to be free of defects in material and workmanship for one year (12 months) from date of authorized start-up, not to exceed eighteen (18) months from date of manufacturer's invoice. Complete terms and conditions will be provided upon request.

3.4 START-UP SERVICE

- A. Owner start up assistance shall be arranged by the distributor. The duration of start-up assistance as well as testing parameters and package capabilities shall be confirmed to the owner by the distributor.

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- 1) The tissue in plants that brings water upward from the roots;
- 2) a leading global water technology company.

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